



STATEMENT

I, Makoto KONDO, of c/o NGB Corporation, ARK Mori Building 13F, 12-32, Akasaka 1-Chome, Minato-ku, Tokyo 107-6013 Japan, hereby state that I am conversant with both the English and Japanese languages and certify to best of my knowledge and belief that the attached is a true and correct English translation of the priority document of Japanese patent application 2003-009434 filed on January 17, 2003.

Date: February 23, 2006

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2006/02/23

JAPAN PATENT OFFICE

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Date of Application: January 17, 2003

Application Number: Patent Application No. 2003-009434

Applicant(s): KOITO MANUFACTURING CO., LTD

December 19, 2003

Commissioner,
Japan Patent Office Yasuo IMAI
Issuance No. 2003-3105502

[DOCUMENT NAME] REQUEST FOR PATENT APPLICATION
[REFERENCE NUMBER] JP02-048
[FILING DATE] January 17, 2003
[ADDRESSEE] COMMISSIONER OF PATENT OFFICE, ESQ.
[IPC] B60Q 01/06
H02K21/12

[TITLE OF INVENTION] BRUSHLESS MOTOR

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[INDICATION OF FEE]

[DEPOSIT ACCOUNT NUMBER] 007009

[AMOUNT OF FEE] ¥21,000.

[LIST OF FILING ITEMS]

[NAME OF ITEM] SPECIFICATION 1

[NAME OF ITEM] DRAWING 1

[NAME OF ITEM] ABSTRACT 1

[PROOF]

NECESSARY

[Designation of Document] Specification

[Title of Invention] Brushless Motor

[Claims]

[Claim 1] A brushless motor comprising a fixedly-supported stator coil, and a rotor including a yoke which is connected to a rotation shaft in a supported manner, and supports a rotor magnet provided around the stator coil; characterized in that there is provided fixing means for fixing the stator coil to a housing or a board, and the fixing means has a positioning structure for positioning the stator coil.

[Claim 2]. A brushless motor comprising a fixedly-supported stator coil, and a rotor including a yoke which is connected to a rotation shaft in a supported manner, and supports a rotor magnet provided around the stator coil; characterized in that there is provided a core base which is integrally connected to a core of the stator coil, and supports the stator coil on a board; and the core base includes engagement means for integrally connecting the core base to the core, and terminals for supporting the core base on the board and for electrically connecting coils, wound on the core, to the board.

[Claim 3] A brushless motor comprising a fixedly-supported stator coil, and a rotor including a yoke which is connected to a rotation shaft in a supported manner, and supports a rotor magnet provided around the stator coil; characterized in that the stator coil can be fitted on a boss which is formed at a

housing, and supports the rotation shaft, and the boss includes means for positioning the stator coil in a circumferential direction and an axial direction, and engagement means for holding a core of the stator coil against movement in an axial direction of the boss.

[Detailed Description of the Invention]

[0001]

[Technical Field]

This invention relates to a brushless motor, and more particularly to a brushless motor in which a positional accuracy in assembling of a stator coil is improved and assembling operation is eased.

[0002]

[Conventional Art]

A brushless motor is not provided with a so-called commutator formed by brushes and a moving contact, and is advantageous in that it can be formed into a compact and lightweight construction. More specifically, Fig. 15 shows a cross-sectional view of a conventional outer rotor-type brushless motor. Identical reference numerals in this Figure and other Figures of preferred embodiments (described later) of the invention denote corresponding portions. A thrust bearing 421 and a sleeve bearing 422 are fitted in a hollow boss 414 formed on an equipment housing 41, and a rotation shaft 423 is rotatably inserted in this sleeve bearing 422. A stator coil

424 is fixedly mounted on the hollow boss 414, and is disposed above a printed circuit board 45 provided within the housing 41. A cylindrical container-like rotor 426 is mounted on the rotation shaft 423, and is rotatably disposed around the stator coil 424. In the stator coil 424, a plurality of coils 4243 are wound on a petal-like core 4241 in such a manner that these coils 4243 are arranged in a circumferential direction so as to produce a plurality of magnetic poles in the circumferential direction. The core 4241 is fitted at its central hole 4244 on the outer periphery of the hollow boss 414, and therefore is supported by this hollow boss. Terminals 4243a of the coils 4243 are electrically connected to the printed circuit board 45, and an alternating current, for example, a three-phase alternating current, is supplied to these coils through the printed circuit board 45. In the rotor 426, an annular rotor magnet 428 is mounted within a cylindrical container-like yoke 427 of metal, cross-sectional view. A plurality of S-poles and N-poles are alternately magnetized in the rotor magnetic 428 in a circumferential direction. The rotation shaft 423 is integrally connected to the yoke 427 through a bushing 4272 fitted in a central hole 4271 in this yoke. A gear 441 for transmitting a rotational force to the exterior is fixedly mounted on a distal end portion of the rotation shaft 423.

[0003]

In this brushless motor, when a three-phase current is

supplied to the stator coil 424, S-poles and N-poles are alternately produced at a plurality of portions of the core 4241 of the stator coil 424 in the circumferential direction. Therefore, a magnetic force, produced between this stator core and the circumferentially-arranged S-poles and N-poles of the rotor magnet 428, changes in accordance with the phase of the three-phase current, and the rotor magnet 428 and the yoke 427, integrally connected thereto, are rotated by this magnetic force. When the yoke 427 thus rotates, the rotation shaft 423 rotates together with this yoke, so that the gear 441, fixedly mounted on the distal end portion of this rotation shaft, is rotated. In the brushless motor, the stator coil 424 for supplying electric power is fixed, and therefore there is no need to provide a commutator for changing the direction of a current flowing through the coils, and this is advantageous in achieving a compact and lightweight design of the motor.

[0004]

For assembling this conventional brushless motor, the stator coil 424, having the coils 4243 wound on the core 4241, is mounted on a predetermined portion of the printed circuit board 45, and then the terminals 424a of the coils 4243 are connected to electrodes on the printed circuit board 45 by soldering or the like, and the stator coil 424 is supported above the printed circuit board 45 in a floating condition. Then, the printed circuit board 45 is mounted within the housing 41.

At this time, the stator coil 424 is fitted on the outer periphery of the hollow boss 414 of the housing 41. On the other hand, in the rotor 426, the bushing 4272 is fitted into the central hole 4271 of the yoke 427 having the rotor magnet 428 mounted therein, and then the yoke is press-fitted on the rotation shaft 423 through the bushing 4272, and therefore is fixed to the rotation shaft 424, and then the gear 441 is press-fitted on the distal end portion of the rotation shaft 423. Then, the thrust bearing 421 and the sleeve bearing 422 are fitted into the hollow boss 414 from the upper side of the printed circuit board 45, and also the proximal end portion of the rotation shaft 423 is inserted into the sleeve bearing 422, so that the rotation shaft 423 is borne by these bearings. As a result, the rotor 426 is mounted in a manner to cover the stator coil 424, so that the assemblage of the brushless motor is completed. This type brushless motor is used in a rotational driving device of a vehicle lamp disclosed in, for example, Patent Document 1.

[0005]

[Patent Document 1] JP-A-2002-160581

[0006]

[Subject to be resolved by the invention]

The conventional brushless motor is of such a construction that the stator coil 424 is fitted on the outer periphery of the hollow boss 414, and therefore it is difficult to highly precisely set the stator coil 424 in its fitted

position relative to the hollow boss 414 in both of the circumferential direction and axial direction of this hollow boss. And besides, the stator coil 424, after fitted on the hollow boss 414, is liable to be moved around the hollow boss 414 by vibrations and an impact, and as a result of this movement, the stator coil 424 is liable to be displaced out of position. Thus, misregistration is liable to develop between the rotor 426 and the stator coil 424, and the intended magnetic force sometimes fails to be produced between the stator coil 424 and the rotor magnet 428 of the rotor 426, which leads to a problem that the rotational force of the motor is lowered. Furthermore, when mounting the stator coil 424 on the printed circuit board 45, the terminals 4243a of the coils 4243 are soldered to the electrodes on the printed circuit board. However, this operation is effected, utilizing a gap formed between the stator coil 424 and the printed circuit board 45, and therefore the soldering operation is difficult, and requires a meticulous attention.

[0007]

The object of the present invention is to provide a brushless motor in which the stator coil is positioned in high accuracy and the assemble operation is easy done.

[0008]

[Means for resolving the subject]

In the present invention, a brushless motor having a

fixedly-supported stator coil, and a rotor including a yoke which is connected to a rotation shaft in a supported manner, and supports a rotor magnet provided around the stator coil, is characterized in that there is provided fixing means for fixing the stator coil to a housing or a board, and the fixing means has a positioning structure for positioning the stator coil.

[0009]

More specifically, there is provided a core base which is integrally connected to a core of the stator coil, and supports the stator coil on a board, and the core base includes engagement means for integrally connecting the core base to the core, and terminals for supporting the core base on the board and for electrically connecting coils, wound on the core, to the board. Alternatively, the stator coil can be fitted on a boss which is formed at the housing, and supports the rotation shaft, and the boss includes means for positioning the stator coil in a circumferential direction and an axial direction, and engagement means for holding the core of the stator coil against movement in an axial direction of the boss.

[0010]

According to the invention, before the stator coil is mounted on the board, the core base is beforehand integrally connected to the core, and terminals of the coils are connected to the terminals, and then the terminals of the core base are

connected to the board, thereby mounting the stator coil on the board. With this construction, the stator coil can be easily mounted on the board, and also the positioning of the stator coil relative to the board can be effected highly precisely by the core base, so that the stator coil can be stably and highly precisely mounted relative to the rotor.

[0011]

In addition, in the invention, when the stator coil is fitted on the boss, the positioning of the stator coil is effected by the positioning means for positioning it in the circumferential and axial directions, and the stator coil is supported on the boss through the engagement means. Therefore, the mounting of the stator coil can be effected easily, and besides the stator coil can be highly precisely located relative to the boss, and can also be highly precisely located relative to the rotor mounted on the boss.

[0012]

[Mode for carrying out the invention]

Next, an exemplary embodiment in which the brushless motor according to the present invention is applied to an Adaptive Front-lighting System (AFS) of a vehicle will be described. In the AFS, information representative of a running condition of an automobile CAR is detected by sensors 1, and detection outputs of these sensors are sent to an electronic control unit (hereinafter referred to as "ECU") 2 as shown in

Fig. 1 which is a conceptual view. For example, as the sensors 1, there are provided a steering sensor 1A for detecting a steering angle of a steering wheel SW of the automobile CAR, a speed sensor 1B for detecting the speed of the automobile CAR, and leveling sensors 1C (only the sensor for a rear axle is shown) for respectively detecting the heights (or levels) of the front and rear axles so as to detect a horizontal condition (leveling) of the automobile CAR. These sensors 1A, 1B and 1C are connected to the ECU 2. In accordance with the outputs of the sensors 1 inputted thereto, the ECU 2 controls swivel lamps 3R and 3L (that is, headlamps 3 each capable of deflecting an illuminating direction right and left to change its luminous distribution characteristics) provided respectively at right and left portions of the front of the automobile. In one known example of such swivel lamp 3R, 3L, a reflector and a projector lamp are provided within the headlamp, and can be angularly moved in a horizontal direction, and these are driven for rotation by a drive power source (such as a drive motor) through rotation drive means. Here, a mechanism, including this rotation drive source, is referred to as an actuator. When a car travels along a curved road, this kind of AFS enables the headlamps to illuminate a road ahead of the curve in accordance with the running speed of the car, and therefore the AFS is effective in enhancing the running safety.

[0013]

Fig. 2 is a vertical cross-sectional view of a headlamp 3 (comprising a swivel lamp 3R, 3L capable of deflecting an illuminating direction right and left, the swivel lamp being a constituent element of an AFS serving as lamp deflection angle control means of the invention), showing an internal structure thereof, and Fig. 3 is a partly-exploded, perspective view of a main portion thereof. A lens 12 is attached to a front open portion of a lamp body 11, and a rear cover 13 is attached to a rear open portion thereof, thereby forming a lamp chamber 14. A projector lamp 30 is provided within the lamp chamber 14. The projector lamp 30 comprise a sleeve 301, a reflector 302, a lens 303, and a light source 304 which are combined together into a unit. This kind of projector lamp has already been extensively used, and therefore detailed description thereof will be omitted here. A discharge bulb is used as the light source 304. The projector lamp 30 is supported by a generally U-shaped bracket 31. An extension 15 is provided around the projector lamp 30 in the lamp body 11 to prevent the interior of the lamp from being viewed through the lens 12. In this embodiment, a lighting circuit 7 for lighting the discharge bulb 304 of the projector lamp 30 is mounted in the lamp by the use of a lower cover 16 attached to a lower open portion of the lamp body 11.

[0014]

The projector lamp 30 is supported by the bracket 31 in

such a manner that this projector lamp is interposed between a lower plate 312 and an upper plate 313 which extend substantially perpendicularly from a vertical plate 311 of the bracket 31. An actuator 4 (described later) is fixedly secured to a lower side of the lower plate 312 by screws 314, and a rotation output shaft 448 of the actuator 4 projects upwardly through a shaft hole 315 formed through the lower plate 312. The screws 314 are screw-fastened respectively to bosses 318 formed on the lower surface of the lower plate 312. A shaft portion 305, formed on an upper surface of the projector lamp 30, is fitted in a bearing 316 provided on the upper plate 313, and a connecting portion 306, provided on a lower surface of the projector lamp 30, is fitted on the rotation output shaft 448 of the actuator 4, and is connected thereto. With this construction, the projector lamp 30 can be angularly moved right and left relative to the bracket 31, and when the actuator 4 is operated, the projector lamp 30 is angularly moved in a horizontal direction together with the rotation output shaft 448.

[0015]

Aiming nuts 321 and 322 are fixedly mounted respectively on upper left and right portions of the bracket 31 (as viewed from the front side), while a leveling bearing 323 is fixedly mounted on a lower left portion of the bracket. A horizontal aiming screw 331 and a vertical aiming screw 332, which are

threadably supported on the lamp body 11, are threaded into the aiming nuts 321 and 322, respectively. A leveling ball 51 of a leveling mechanism 5, supported on the lamp body 11, is fitted in the leveling bearing 323. With this construction, by threading the horizontal aiming screw 331, the bracket 31 can be angularly moved in the horizontal direction about an axis passing through the right aiming nut 322 and the leveling bearing 323. By threading the horizontal aiming screw 331 and the vertical aiming screw 332 at the same time, the bracket 31 can be angularly moved upward and downward about the leveling bearing 323. When the leveling mechanism 5 is operated, the leveling ball 51 is moved forward and backward in an axial direction, and by doing so, the bracket 31 can be angularly moved upward and downward about an axis passing through the left and right aiming nuts 321 and 322. With this construction, the aiming adjustments for adjusting the optical axis of the projector lamp 30 in the left and right directions and the upward and downward directions can be effected, and also there can be effected the leveling adjustment for adjusting the optical axis of the projector lamp in the upward and downward directions in accordance with a leveling condition changing with a change of a car height. A projection 307 is formed on a lower surface of the reflector 302 of the projector lamp 30, and a pair of stamped-out stoppers 317 are formed respectively at left and right sections of that portion of the lower plate 312 (of the

bracket 31) generally opposed to the projection 307. When the projector lamp 30 is angularly moved, the projection 307 is brought into engagement with one of the stoppers 317, thereby limiting the range of angular movement of the projector lamp 30.

[0016]

Fig. 4 is an exploded, perspective view of a main portion of the actuator 4 for swiveling the swivel lamp 3R, 3L, and Fig. 5 is a plan view showing the construction of the actuator in its assembled condition, and Fig. 6 is a vertical cross-sectional view thereof. A casing 41 is formed by a lower half portion 41D and an upper half portion 41U each having a generally-pentagonal dish-like shape. A plurality of projections 410, formed on a peripheral surface of the lower half portion 41D, are fitted respectively in a plurality of fitting piece portions 411 extending downwardly from a peripheral surface of the upper half portion 41U, so as to forming a casing room. In addition, support piece portions 412, 413 are formed on and project from side surfaces of the upper half portion 41U and side surfaces of the lower half portion 41D, respectively. These support piece portions 412 and 413 are used to fix the casing 41 to the bracket 31 through the screws 314 as described above. The rotation output shaft 448, having splines, projects from the upper surface of the casing 41, and is connected to the connecting portion 306 provided at the

bottom surface of the projector lamp 30. A connector 451 is provided at a bottom side of the casing 41. An external connector 21 (see Fig. 2), connected to an ECU2, is adapted to be fittingly connected to this connector 451.

[0017]

Four hollow bosses 414, 415, 416 and 417 are formed upright respectively on predetermined portions of an inner bottom surface of the lower half portion 41D of the casing 41. A brushless motor 42 (described later), serving as a drive motor, is assembled on the first hollow boss 414. Shafts of a gear mechanism 44 (described later) are inserted and supported in the second to fourth hollow shafts 415, 416 and 417, respectively. A step-like rib 418 is formed integrally on a peripheral edge portion of the inner bottom surface of the lower half portion 41D over an entire periphery thereof, and a printed circuit board 45 is placed at its peripheral edge portion on the step-like rib 418, and the printed circuit board 45 is mounted and supported within the casing 41 in such a manner that this printed circuit board 45 is held between the step-like rib 418 and a downwardly-directed rib (not shown) formed on the upper half portion 41U. The first hollow boss 414 passes through the printed circuit board 45, and the assembled brushless motor 42 is electrically connected to the printed circuit board 45, and various electronic parts (not shown) of a control circuit 43 (described later) and the connector 451

are mounted on the printed circuit board 45.

[0018]

In the brushless motor 42, as shown in Fig .4, a rotation shaft 423 is rotatably supported in the first hollow boss 414 of the lower half portion 41D through a thrust bearing 421 and a sleeve bearing 422. A stator coil 424, including three pairs of coils equally spaced in a circumferential direction, is fixedly mounted on the printed circuit board 45 which is supported on the lower half portion 41D, with the first hollow boss 414 passing therethrough. The stator coil 424 is electrically connected to the printed circuit board 45 so as to be supplied with electric power. Here, the stator coil 424 is integrally combined with a core base 425, and is electrically connected to the printed circuit board 45 via terminals 425a formed at the core base 425. A cylindrical container-like rotor 426 is fixedly mounted on an upper end portion of the rotation shaft 423 in surrounding relation to the stator coil 424. The rotor 426 comprises a resin-molded yoke 427 of a cylindrical container-shape, and an annular rotor magnet 428 which is mounted on an inner surface of the yoke 427, and has S-poles and N-poles alternately magnetized therein in a circumferential direction.

[0019]

Fig. 7 is a partly-exploded, perspective view showing the stator coil 424 and the core base 425, and Fig. 8 is a

partly-broken, partly-exploded perspective view of the rotor 426. Fig. 9 is a cross-sectional view of the brushless motor 42 incorporating the stator coil 424. The stator coil 424 includes a petal-like core 4241 having 6 radial arms 4242, and the coils 4243 are wound on the radial arms 4242, respectively. Each pair of diametrically-opposite coils 4243 are serially connected, so that the three pairs of coils are provided. Three fitting grooves 4245 are formed in an inner surface of a central hole 4244 in the core 4241, and are spaced from one another in a circumferential direction, and extend in an axial direction, each fitting groove 4245 being recessed toward the outer periphery of the core.

[0020]

The core base 425 includes an annular portion 4251, and three narrow fitting support piece portions 4252 are formed integrally with and project axially from one surface of the annular portion 4251, and are circumferentially spaced from one another. Three short support seats 4253 are formed integrally with and project axially from the one surface of the annular portion 4251, the support seat 4253 being provided between any two adjacent fitting support piece portions 4252. A hook 4254 is formed at a distal end of each fitting support piece portion 4252, and the fitting support piece portions 4252, when passed through the central hole 4244 in the core 4241, are fitted respectively in the fitting grooves 4245, respectively, and the

hooks 4254 are engaged with one edge of the core 4241, so that the core 4241 is held between the hooks 4254 and the support seats 4253, thereby integrally combining the core base 425 and the stator coil 424 together. Two legs 4255 are formed integrally with and project axially respectively from two of six circumferentially-equally-divided sections of the other surface of the annular portion 4251 of the core base 425, and the terminals 425a, each comprising an electrically-conductive wire (metal wire) having a bent portion, extend respectively through the other four sections of the annular portion 4251, and are supported by this annular portion 4251, and distal end portions of the terminals 425a project from the annular portion 4251. Recesses 4256 are formed respectively in the inner peripheral surface of the core base, and are disposed respectively at those portions of the core base through which the terminals 425a extend, respectively. Those portions of the annular portion 4251, in which the recesses 4256 are formed, respectively, are radially reduced in thickness. Three terminals 425a1 to 425a3 (disposed adjacent to one another in the circumferential direction) among the four terminals 425a are provided as separate terminals, respectively, and a terminal 4243a of one of each pair of coils 4243 is electrically connected by soldering to a proximal end of the corresponding terminal 425a1, 425a2, 425a3. The remaining terminal 425a4 serves as a common terminal, and a terminal 4243a of the other

of each pair of coils 4243 is electrically connected to a proximal end of this common terminal by soldering.

[0021]

When the fitting support piece portions 4252 of the core base 425 (which is separate from the stator coil 424) are passed respectively through the fitting grooves 4245 in the core 4241, the hooks 4254 of the fitting support piece portions 4252 are engaged with the one edge of the core 4241, so that the core 4241 is held between the support seats 4253 on the core base 425 and the hooks 4254, thereby integrally combining the core base and the core together. At this time, the support seats 4253 are held against the other end or edge of the core 4241, thereby positioning the core 4241 relative to the core base 425. The terminals 4243a of the three pairs of coils 4243 are electrically connected to the three separate terminals 425a1 to 425a3 and one common terminal 425a4, and then the distal end portions of the terminals 425a1 to 425a4 are passed respectively through holes 452 in the printed circuit board 45 until the two legs 4255 are brought into contact with the surface of the printed circuit board 45. Then, the distal end portions of these terminals are soldered to circuit electrodes on the reverse surface of the printed circuit board 45. By doing so, the core base 425 is mounted on the printed circuit board 45, and the electrical connection to the coils 4243 is effected. As a result, the core base 425 is fixedly supported on the printed

circuit board 45 in such a manner that the core base 425 is positioned relative to the printed circuit board 45 through the legs 4255. Also, the stator coil 424 is stably supported in such a manner that the stator coil 424 is positioned relative to the printed circuit board 45, and in this condition, the stator coil can be supplied with electric power via the printed circuit board 45. In this embodiment, the distal end portions of the three separate terminals 425a1 to 425a3 are soldered to the printed circuit board 45, but the solders on the distal end portions of these terminals will not be melted since the terminals of the coils are soldered to the proximal ends of these terminals 425a1 to 425a3. The single common terminal 425a4 to which the terminals of the coils are electrically connected does not need to be connected to an external portion, and therefore is not soldered to the printed circuit board 45. Therefore, a solder-melting problem is not encountered even when the terminals of the three coils are soldered to the distal end portion of the common terminal 425a4. Even when a stress is transmitted from the printed circuit board 45 to the terminals 425a1 to 425a4 after the soldering, this stress will not adversely affect the stator coil 424 through the annular portion 4251 since those portions of the annular portion 425 through which the terminals pass, respectively, are reduced in thickness by the recesses 4256.

[0022(434)]

On the other hand, the rotor 426, fixedly mounted on the upper end portion of the rotation shaft 423, is disposed to cover the outer periphery and upper side of the stator coil 424 as shown in Figs. 4 and 8. As described above, the rotor 426 comprises the resin-molded yoke 427 of a cylindrical container-shape, and the annular rotor magnet 428 which is mounted on the inner surface of the yoke 427, and has the S-poles and N-poles alternately magnetized therein in the circumferential direction. A first gear 441 of the gear mechanism 44 (described later) is formed integrally with and projects from a central portion of a circular outer surface of the yoke 427, and the rotation shaft 423 is fitted in a shaft hole 4270, formed through the first gear 441, and is integrally combined therewith.

[0023]

As shown in Fig. 7, a plurality of (three in this embodiment) Hall elements or Hall ICs (hereinafter referred to as "Hall ICs") H1, H2 and H3 are mounted on the printed circuit board 45, and are arranged at predetermined intervals in the direction of the circumference of the rotor 426. When the rotor magnet 428 rotates together with the rotor 426, a magnetic field at each of the Hall ICs H1, H2 and H3 is changed, and each Hall IC H1, H2, H3 is changed between an ON-state and an OFF-state, and outputs a pulse signal corresponding to a rotation period of the rotor 426.

[0024]

The first gear 441, resin-molded integrally with the yoke 427 of the rotor 426, forms part of the gear mechanism 44, and is designed to drive and rotate the rotation output shaft 448 in a speed-reducing manner. Namely, the gear mechanism 44 includes the first gear 441, a second gear 443 rotatably mounted on a first fixed shaft 442 supported in the second hollow boss 415, a third gear 445 rotatably mounted on a second fixed shaft 444 supported in the third hollow boss 416, and a sector gear 447 which is rotatably supported on a third fixed shaft 446 supported in the fourth hollow boss 417, and is formed integrally with the rotation output shaft 448. Each of these gears is molded of a resin. As shown in Figs. 5 and 6, the second gear 443 includes a second larger-diameter gear 443a and a second smaller-diameter gear 443b which are integrally formed with each other, and are arranged in an axial direction, the second larger-diameter gear 443a being in mesh with the first gear 441. The third gear 445 includes a third larger-diameter gear 445a and a third smaller-diameter gear 445b which are integrally formed with each other, and are arranged in an axial direction, the third larger-diameter gear 445a being in mesh with the second smaller-diameter gear 443b. The third smaller-diameter gear 445b is in mesh with the sector gear 447. With this construction, a rotational force of the first gear 441, rotating together with the rotor 427 of the brushless motor

42, is reduced through the second gear 443, the third gear 445 and the sector gear 447, and is transmitted to the rotation output shaft 448. Stoppers 419 are formed on and project from the inner surface of the lower half portion 41D, and are disposed respectively at opposite ends of a path of rotation of the sector gear 447, and opposite ends of the sector gear 447 can be brought into abutting engagement with the stoppers 491, respectively. These stoppers 419 limit the range of angular movement of the sector gear 447 and hence the range of angular movement of the rotation output shaft 448.

[0025]

Fig. 9 is a block diagram of the electric circuit of the lighting unit including the ECU 2 and the actuator 4. The actuator 4 is provided in each of the right and left swivel lamps 3R and 3L of the car, and a two-way communication can be effected between the actuator 4 and the ECU2. The ECU 2 includes a main CPU 201 for effecting a processing on the basis of information from the sensors 1 according to a predetermined algorithm to output a required control signal C0, and an interface (hereinafter referred to as "I/F") circuit 202 for inputting and outputting the control signal C0 between the main CPU 201 and the actuator 4. An ON/OFF signal from a lighting switch S1, provided at the car, can be inputted into the ECU 2, and in accordance with the ON/OFF state of the lighting switch S1, the ECU 2 controls the lighting circuit 7 (connected to an

on-vehicle power source (not shown) so as to supply electric power to the discharge bulb 304 of the projector lamp 30) by a control signal N so as to turn on and off the swivel lamp 3R, 3L. The ECU 2 controls a leveling control circuit 6 (for controlling the leveling mechanism 5 for adjusting the optical axis of the bracket (supporting the projector lamp 30) in the upward-downward direction) by a leveling signal DK so as to adjust the optical axis of the projector lamp 30 in accordance with a change of the car height. Naturally, the condition of connection of these electric circuits to the power source is turned on and off by an ignition switch S2 for turning on and off an electric system provided at the car.

[0026]

The control circuit 43, provided on the printed circuit board 45 contained in the actuator 4 mounted in each of the right and left swivel lamps 3R and 3L of the car, includes an I/F circuit 432 for inputting and outputting a signal between the control circuit 43 and the ECU 2, a sub-CPU 431 for effecting a processing on the basis of a signal from the I/F circuit 432 and pulse signals from the Hall ICs H1, H2 and H3 according to a predetermined algorithm, and a motor drive circuit (rotation drive means) 434 for driving and rotating the brushless motor 42. The ECU 2 outputs a right-left deflection angle signal DS (which is part of the control signal CO) representative of a right-left deflection angle of the swivel lamp 3R, 3L, and this

signal is inputted to the actuator 4.

[0027]

Fig. 10 is a circuit diagram schematically showing the motor drive circuit 434 of the control circuit 43 and the brushless motor 42 in the actuator 4. The motor drive circuit 434 includes a switching matrix circuit 435, and an output circuit 436. As control signals, a speed control signal V, a start/stop signal S and a normal/reverse rotation signal R from the sub-CPU 431 of the control circuit 43, as well as pulse signals from the three Hall ICs H1, H2 and H3, are inputted into the switching matrix circuit 435. The output circuit 436 is responsive to an output of the switching matrix circuit 435 to adjust the phases of three-phase (U-phase, V-phase and W-phase) electric powers which are to be supplied respectively to the three pairs of coils of the stator coil 424 of the brushless motor 42. In this motor drive circuit 434, the U-phase, V-phase and W-phase powers are supplied to the stator coil 424, thereby rotating the rotor magnet 428, and therefore the yoke 427 (integral with this rotor magnet), that is, the rotor 426 and the rotation shaft 423, rotate. When the magnet rotor 428 rotates, the Hall ICs H1, H2 and H3 detect a change of the magnetic field to output pulse signals P, respectively, and these pulse signals P are inputted into the switching matrix circuit 435, and in this switching matrix circuit 435, a switching operation for the output circuit 436 is effected in

accordance with the timings of the pulse signals, so that the rotor 426 continues to rotate.

[0028]

In accordance with the speed control signal V, the start/stop signal S and the normal/reverse rotation signal R from the sub-CPU 431, the switching matrix circuit 435 feeds a required control signal C1 to the output circuit 436. In response to this control signal C1, the output circuit 436 adjusts the phases of the three-phase powers (which are to be supplied to the stator coil 424), and controls the start and stop of the rotation of the brushless motor 42, the direction of rotation thereof and the speed of rotation thereof. Part of each of the pulse signals P, outputted respectively from the Hall ICs H1, H2 and H3, is inputted into the sub-CPU 431, so that this sub-CPU recognizes the rotating condition of the brushless motor 42. An up-down counter 437 is contained in the sub-CUP 431, and the pulse signals from the Hall ICs H1, H2 and H3 are counted, so that the value of this count corresponds to the rotational position of the brushless motor 42.

[0029]

In the above construction, when the ignition switch S2 is turned on, and also the lighting switch S1 is turned on, information, representing the steering angle of the steering wheel SW, the speed of the car, the car height of the car, etc., is inputted into the ECU 2 from the sensors 1 mounted on the

car as shown in Fig. 1. In the ECU 2, the main CPU 201 effects a computing operation on the basis of the sensor outputs inputted thereto, and computes the right-left deflection angle signal DS of the projector lamp 30 of each of the swivel lamps 3R and 3L of the car, and these signals DS are inputted respectively to the actuators 4 of the two swivel lamps 3R and 3L. In the actuator 4, the sub-CPU 431 effects a computing operation on the basis of the right-left deflection angle signal DS inputted thereto, and computes a signal corresponding to this right-left deflection angle signal DS, and this computed signal is fed to the motor drive circuit 434, thereby driving and rotating the brushless motor 42. A rotation drive force of the brushless motor 42 is reduced in speed by the reduction gear mechanism 44, and is transmitted to the rotation output shaft 448. Therefore, the projector lamp 30, connected to the rotation output shaft 448, is angularly moved in the horizontal direction, so that the optical axis of the swivel lamp 3R, 3L is deflected right and left. When the projector lamp 30 is thus angularly moved, the angle of deflection of the projector lamp 30 is detected by the angle of rotation of the brushless motor 42. Namely, the sub-CPU 431 detects this deflection angle on the basis of the pulse signals P (P1, P2 and P3) outputted from the three Hall ICs H1, H2 and H3 provided at the brushless motor 42 as shown in Fig. 10. Further, the sub-CPU 431 compares the right-left deflection angle signal DS, inputted thereto from

the ECU2, with a detection signal representative of the detected deflection angle, and effects a feedback control of the rotation angle of the brushless motor 42 so that the two can coincide with each other, and by doing so, the optical axis of the projector lamp 30, that is, the optical axis of the swivel lamp 3R, 3L, can be highly precisely brought into a deflection position set by the right-left detection angle signal DS.

[0030]

In this deflecting operation for the projector lamp 30, deflected light, emitted from the swivel lamp 3R, 3L, illuminates a zone deflected right or left from a direction of straight travel of the car, and therefore during the travel of the car, each lamp can illuminate a zone ahead of the car not only in the direction of straight travel of the car but also in a direction toward which the car is steered, and therefore the driving safety can be enhanced.

[0031]

In the brushless motor 42, before the stator coil 424 is mounted on the printed circuit board 45, the core base 425 is beforehand integrally combined with the core 4241, and the terminals of the coils 4243 are soldered to the terminals 425a1 to 425a4, and then the terminals 425a1 to 425a4 of the core base 425 are passed respectively through the holes 452 in the printed circuit board 45, and the these terminals are soldered to the reverse surface of the printed circuit board 45, thereby

mounting the stator coil on the printed circuit board. Therefore, the mounting and soldering of the stator coil 424 relative to the printed circuit board 45 can be effected easily, and besides the stator coil 424 can be highly precisely positioned relative to the printed circuit board 45 by the core base 425. Therefore, when the printed circuit board 45 is mounted in the predetermined position within the housing 41 in such a manner that this printed circuit board is fixedly held between the upper and lower half portions 41U and 41D, the stator coil 424 can be mounted on the first hollow boss 414 in highly-precisely positioned relation thereto.

[0032]

Fig. 11 is a partly-exploded, perspective view showing a support structure of a stator coil 424 of a second embodiment of the invention, and Fig. 13 is a cross-sectional view of a brushless motor employing this stator coil 424, showing its assembled condition. In this embodiment, although the stator coil 424 is directly fitted and supported on a first hollow boss 414 of a housing 41 as in the conventional construction, the precision of positioning of the stator coil relative to the first hollow boss 414, as well as the stability of supporting of the stator coil on the first hollow boss 414, is enhanced. Three radially inwardly-projecting keys 4246 are formed on an inner surface of a central hole 4244 in a core 4241 of the stator coil 424, and are spaced from one another in a circumferential

direction, and extend in an axial direction. On the other hand, three key grooves 4141, corresponding respectively to the keys 4246, are formed in an outer peripheral surface of the first hollow boss 414 of the housing 41 at a distal end portion thereof, and are spaced from one another in a circumferential direction, and extend a predetermined distance from the distal end of this boss 414 in an axial direction. Also, three tongue-like retaining piece portions 4142 (each of which can be elastically deformed in a radial direction, and has a hook 4143 formed at its distal end) are formed on the outer peripheral surface of the first hollow boss 414, the retaining piece portion 4142 being disposed between any two adjacent key grooves 4141 spaced from each other in the circumferential direction. Here, the retaining piece portions 4142 are disposed respectively in grooves 4144, formed in the outer peripheral surface of the first hollow boss 414, so as to be elastically deformed radially of this hollow boss 414.

[0033]

In this construction, terminals 4243a of coils 4243 are soldered to electrodes 453 on a printed circuit board 45, so that the stator coil 424 is supported above the printed circuit board 45 in a floating condition thanks to the rigidity of these terminals as in the conventional construction. Then, the printed circuit board 45 is mounted in a lower half portion 41D of the housing 41, and at this time the stator coil 424 is fitted

on the first hollow boss 414 in such a manner that the keys 4246 of the stator coil 424 are fitted respectively in the key grooves 4141 in the first hollow boss 414. As a result, the core 4214 of the stator coil 424 abuts at its lower edge against lower end surfaces of the key grooves 4141, and at the same time the hooks 4143 of the retaining piece portions 4142 are engaged with the upper edge portion of the central hole in the core 4241. Therefore, the positioning of the stator coil 424 in the circumferential direction is effected by the keys 4246 and the key grooves 4141, and also the stator coil is prevented by the hooks 4143 of the retaining piece portions 4142 from being disengaged from the first hollow boss 414. Therefore, in this second embodiment, some time and labor are required for mounting the stator coil 424 on the printed circuit board 45, but when the stator coil 424 is thereafter mounted within the housing, the stator coil 424 is highly precisely located relative to the first hollow boss 414, and also is stably and highly precisely located relative to a rotor 426 mounted on the first hollow boss 414.

[0034]

Fig. 13 is a partly-exploded, perspective view showing a third embodiment of a stator coil 424 of the invention which is a modification of the second embodiment, and Fig. 14 is a cross-sectional view of a brushless motor employing this stator coil 424, showing its assembled condition. This modification

is identical to the second embodiment in that keys 4246 are formed on an inner surface of a central hole 4244 in a core 4241 of the stator coil 424. On the other hand, this modification differs from the second embodiment in that engagement piece portions 4145, each having a hook 4146 formed at its distal end, are provided respectively at circumferentially-spaced portions of a first hollow boss 414 corresponding respectively to the keys 4246. More specifically, slots 4147 of a predetermined length are formed respectively through those circumferentially-spaced portions of a peripheral wall of the first hollow boss 414 corresponding respectively to the keys 4246, and extend from a distal end of this first hollow boss 414. The tongue-like engagement piece portions 4145 are formed in these slots 4147, respectively. Inner surfaces of the engagement piece portions 4145 extend along an inner peripheral surface of a shaft hole 4148 in the first hollow boss 414.

[0035]

In this third embodiment, the stator coil 424 is mounted on a printed circuit board 45, and simultaneously when the printed circuit board 45 is mounted within a lower half portion 41D, the stator coil 424 is fitted on the first hollow boss 414 as described above for the second embodiment. At this time, each of the keys 4246 advances in and along the corresponding slot 4147 while elastically deforming the corresponding engagement piece portion 4145 radially inwardly. Then, when

the keys 4246 abut respectively against lower end surfaces of the slots 4147, the engagement piece portions 4145 are elastically restored radially outwardly, so that the hooks 4146 are brought into engagement with the upper edge of the core 4241, and therefore the stator coil 424 is mounted on the first hollow boss 414 in such a manner that the stator coil 424 is held against movement in the axial direction. At this time, the stator coil 424 is positioned in the circumferential direction and axial direction by the keys 4246 and the slots 4147. The disengagement of the stator coil 424 from the first hollow boss 414 is prevented by the hooks 4146 of the engagement piece portions 4145 engaged with the upper edge of the stator coil 424. Therefore, in this third embodiment, some time and labor are required for mounting the stator coil 424 on the printed circuit board 45, but when the stator coil 424 is thereafter mounted within the housing, the stator coil 424 is highly precisely located relative to the first hollow boss 414, and also is stably and highly precisely located relative to a rotor 426 mounted on the first hollow boss 414. In this third embodiment, when a sleeve bearing 422 is press-fitted into the shaft hole 4148 in the first hollow boss 414 after the stator coil 424 is fitted on the first hollow boss 414, the inner surfaces of the engagement piece portions 4245 are held in contact with an outer peripheral surface of the sleeve bearing 422, so that the engagement piece portions 4245 are prevented

from being elastically deformed radially inwardly, and therefore the hooks 4246 will not be disengaged from the upper edge of the stator coil 424, thereby positively preventing the disengagement of the stator coil 424.

[0036]

In the above embodiments, although the brushless motor of the invention is used as the actuator for driving the swivel lamp of the AFS, the brushless motor can be used for other purposes.

[0037]

[Advantage of the invention]

In the invention, before the stator coil of the brushless motor is mounted on the board, the core base is beforehand integrally connected to the core, and the terminals of the coils are connected to the terminals, and then the terminals of the core base are connected to the board, thereby mounting the stator coil on the board. With this construction, the stator coil can be easily mounted on the board, and also the positioning of the stator coil relative to the board can be effected highly precisely by the core base, so that the stator coil can be stably and highly precisely mounted relative to the rotor.

[0038]

In the invention, when the stator coil is fitted on the boss supporting the rotation shaft, the positioning of the stator coil is effected by the positioning means for positioning

it in the circumferential and axial directions, and the stator coil is supported on the boss through the engagement means. Therefore, the mounting of the stator coil can be effected easily, and besides the stator coil can be highly precisely located relative to the boss, and can also be highly precisely located relative to the rotor mounted on the boss.

[Brief Description of the Drawings]

[Fig. 1]

Fig. 1 is a view showing a conceptual construction of an AFS.

[Fig. 2]

Fig. 2 is a vertical cross-sectional view of a swivel lamp.

[Fig. 3]

Fig. 3 is an exploded, perspective view showing an internal structure of the swivel lamp.

[Fig. 4]

Fig. 4 is a partly-exploded, perspective view of an actuator.

[Fig. 5]

Fig. 5 is a plan view of the actuator.

[Fig. 6]

Fig. 6 is a vertical cross-sectional view of the actuator.

[Fig. 7]

Fig. 7 is a partly-exploded, perspective view of a stator coil.

[Fig. 8]

Fig. 8 is a cross-sectional view showing an important portion of a brushless motor.

[Fig. 9]

Fig. 9 is a block circuit diagram showing a circuit construction of the AFS.

[Fig. 10]

Fig. 10 is a circuit diagram showing a circuit construction of the actuator.

[Fig. 11]

Fig. 11 is a partly-exploded, perspective view of a stator coil of a second embodiment.

[Fig. 12]

Fig. 12 is a cross-sectional view of a brushless motor of the second embodiment.

[Fig. 13]

Fig. 13 is a partly-exploded, perspective view of a stator coil of a third embodiment.

[Fig. 14]

Fig. 14 is a cross-sectional view of a brushless motor of the third embodiment.

[Fig. 15]

Fig. 15 is a cross-sectional view of a portion of a conventional brushless motor.

[Description of Reference Numeral]

1 a sensor
2 an ECU
3 a headlamp
3L and 3R swivel lamps
4 an actuator
5 a leveling mechanism
7 a lighting circuit
41 a casing
42 a brushless motor
45 a printed circuit board
414 a first hollow boss
424 a stator coil
425 a core base
426 a rotor
427 a yoke
428 a rotor magnet
4141 a key groove
4142 an engagement piece portion
4145 an engagement piece portion
4241 a core
4243 a coil
4243a a terminal
4246 a key
4251 an annular portion
4252 an engagement piece portion
425a1 to 425a4 terminals
H1 H2 and H3 Hall ICs
S1 an ignition switch

S2 a lighting switch.

[Designation of Document]

Abstract

[Abstract]

[Problem] In a brushless motor provided with a rotor and a stator coil, to carry out a positioning the stator coil in high accuracy so as to supported on a board or the like, and to ease an assembling operation.

[Means for Resolution] In a brushless motor 42 provided with a fixedly-supported stator coil 424, and a rotor 426 including a yoke 427 which is connected to a rotation shaft 423 and supports a rotor magnet 428 provided around the stator coil, there is provided fixing means for fixing the stator coil to a board 45 or the like. The fixing means is provided with a core base 425 which is integrally connected to a core 4241 of the stator coil, and the core base 425 includes engagement means integrally connected to the yoke 427, and terminals 425a1 to 425a4 for supporting the core base 425 on the board 45 and for electrically connecting coils 4253 wound on the core to the board 45.

[Selected Drawing]

Fig. 8

FIG. 1

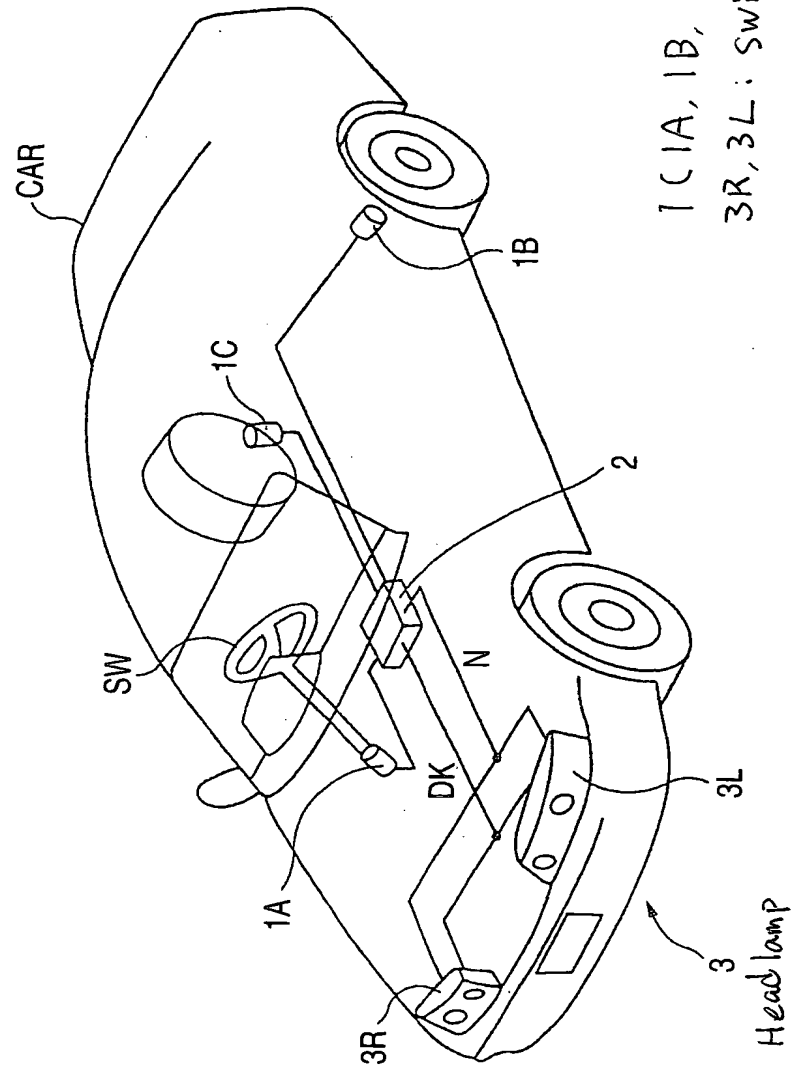


FIG. 2

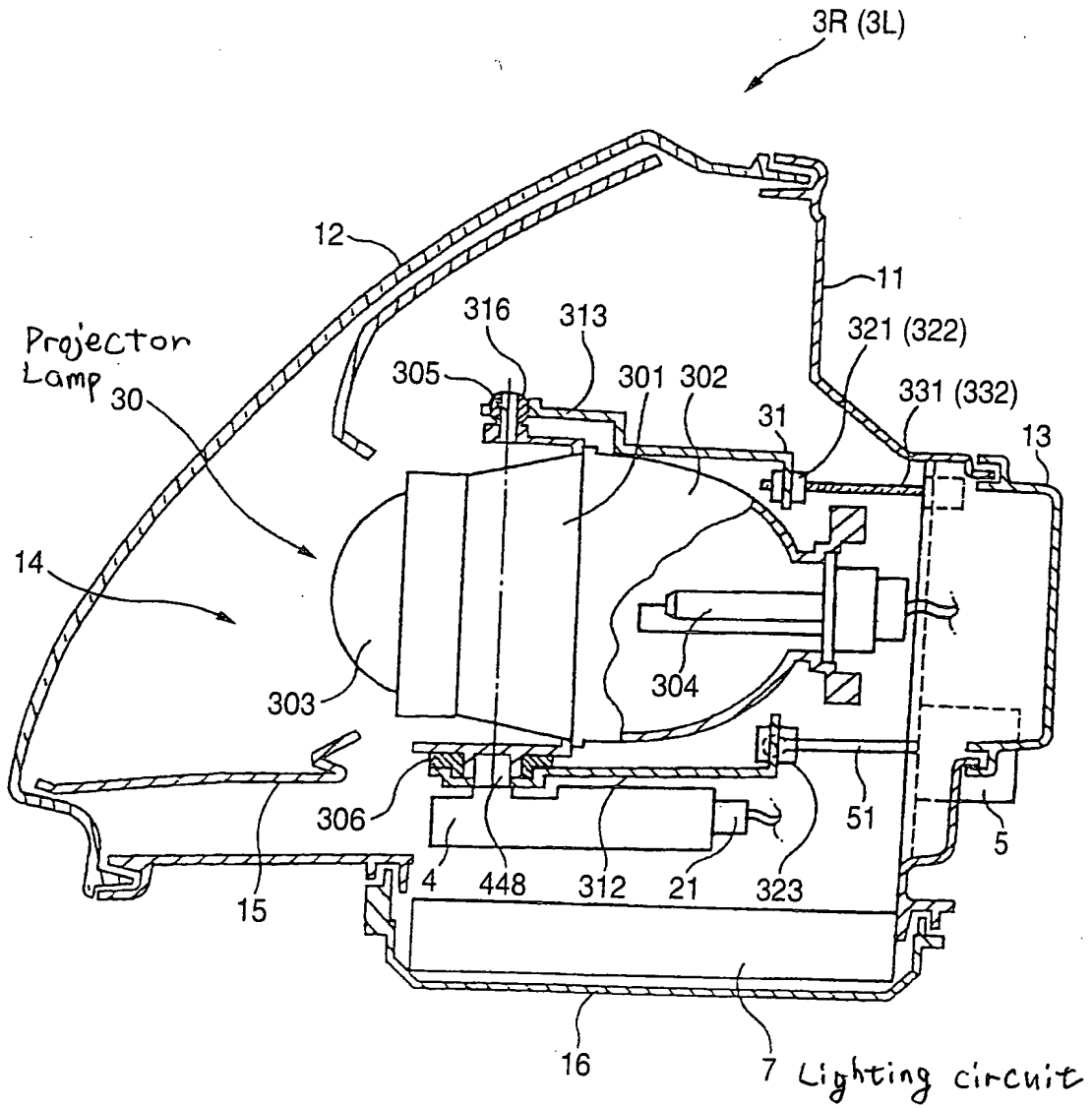


FIG. 3

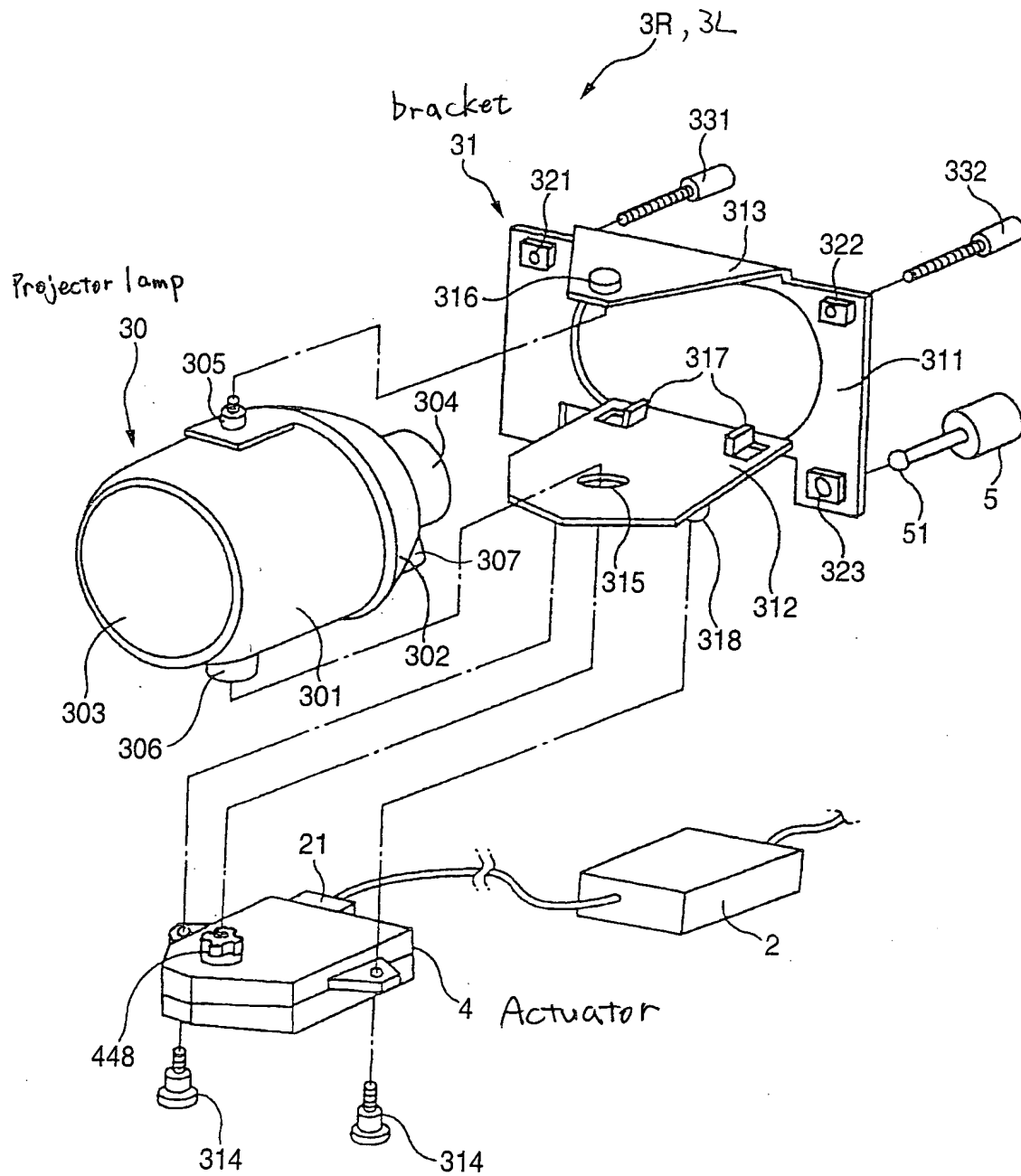


FIG. 4

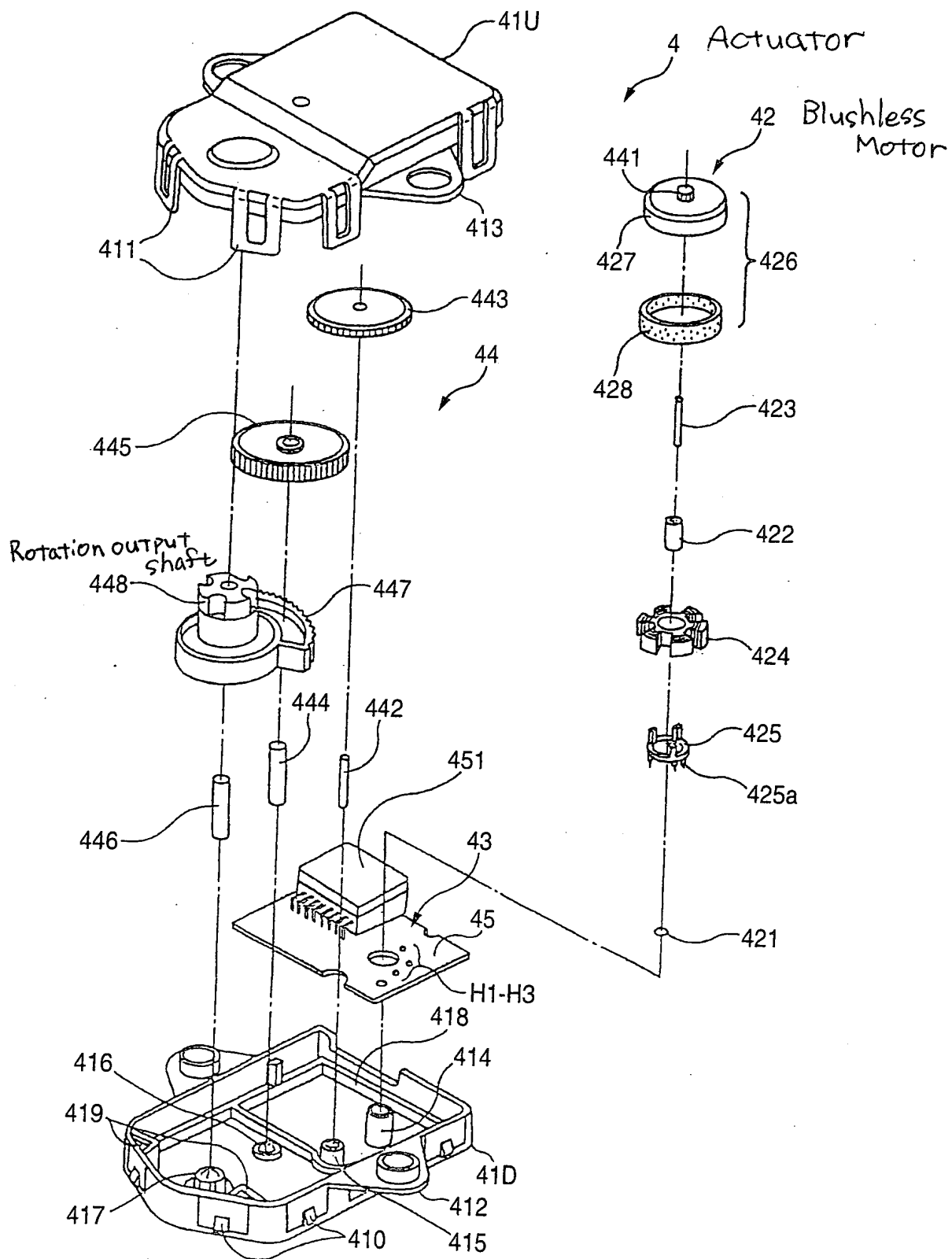


FIG. 5

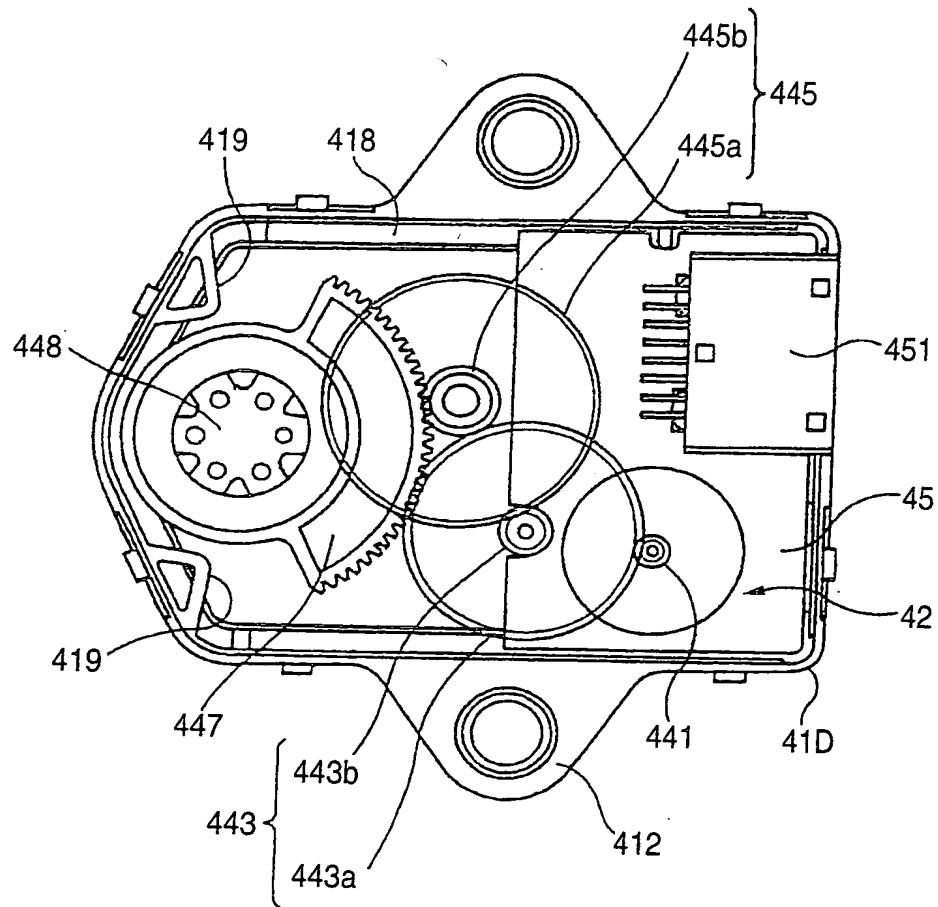


FIG. 6

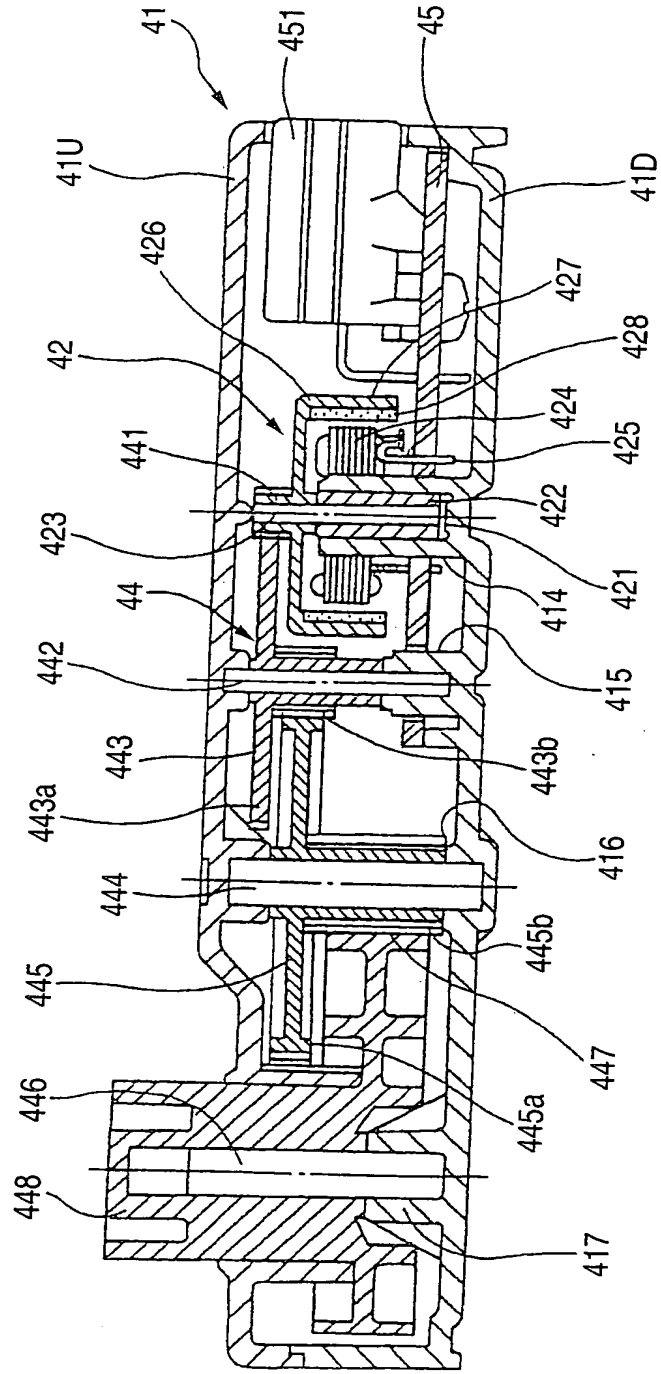
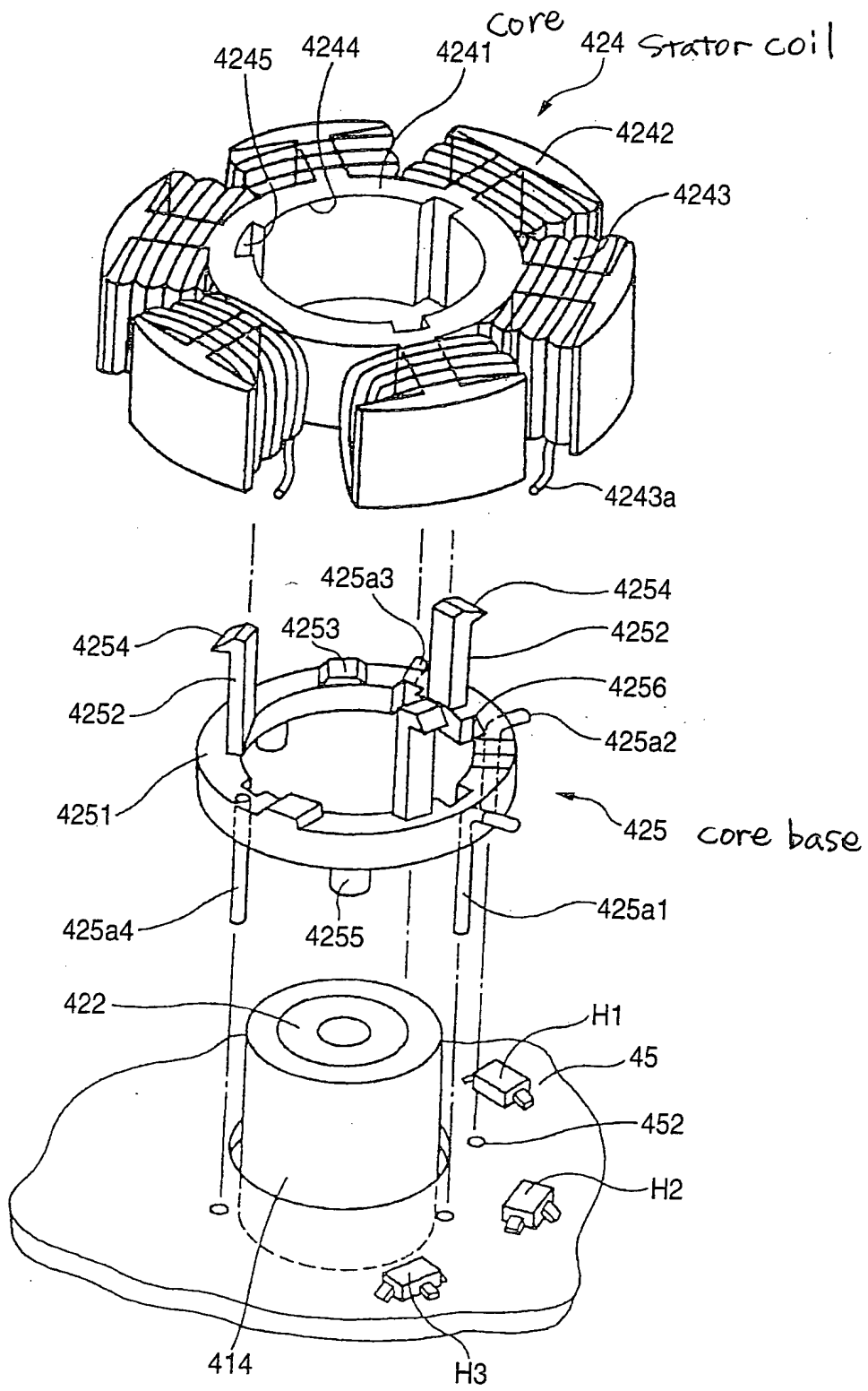


FIG. 7



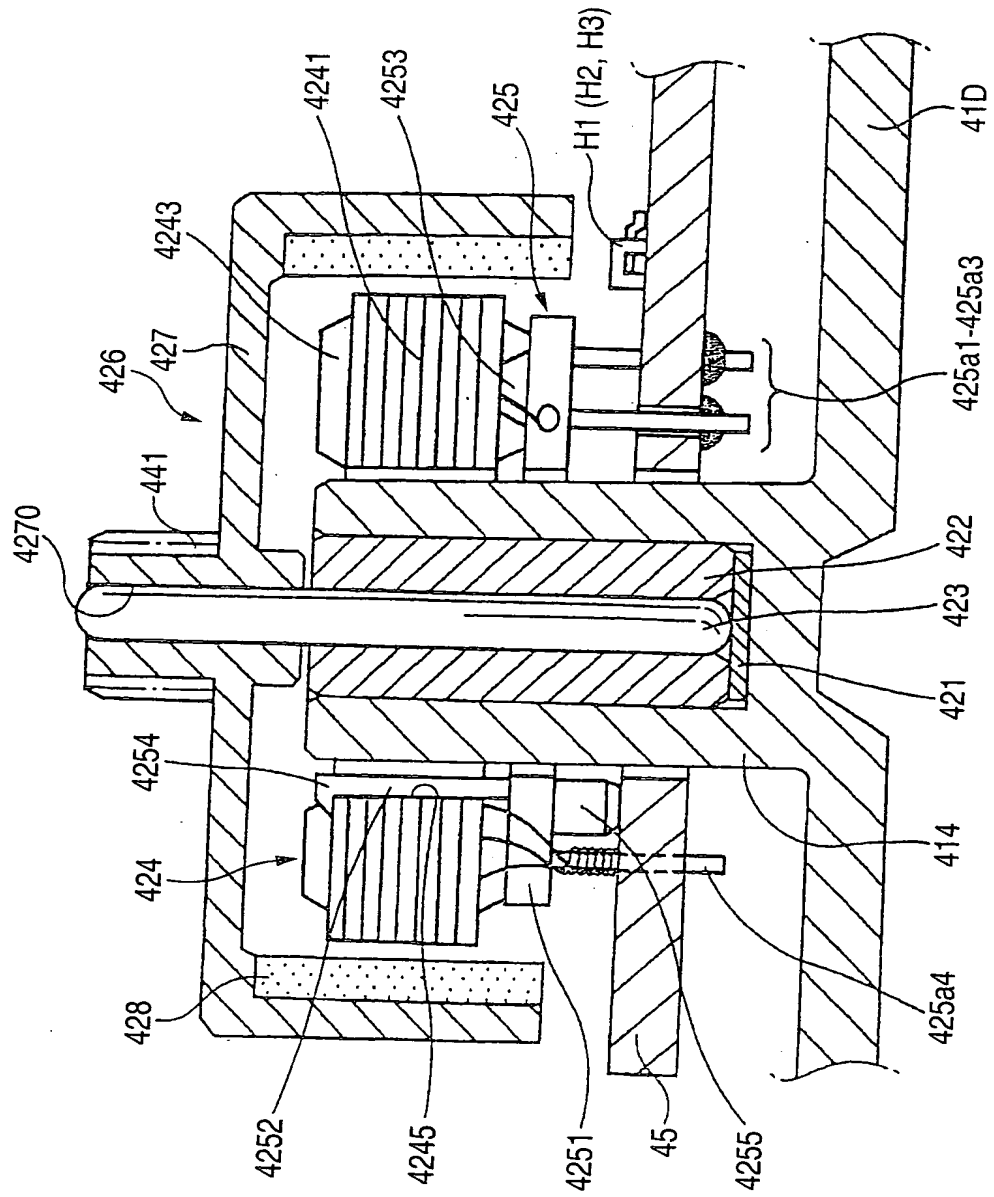


FIG. 9.

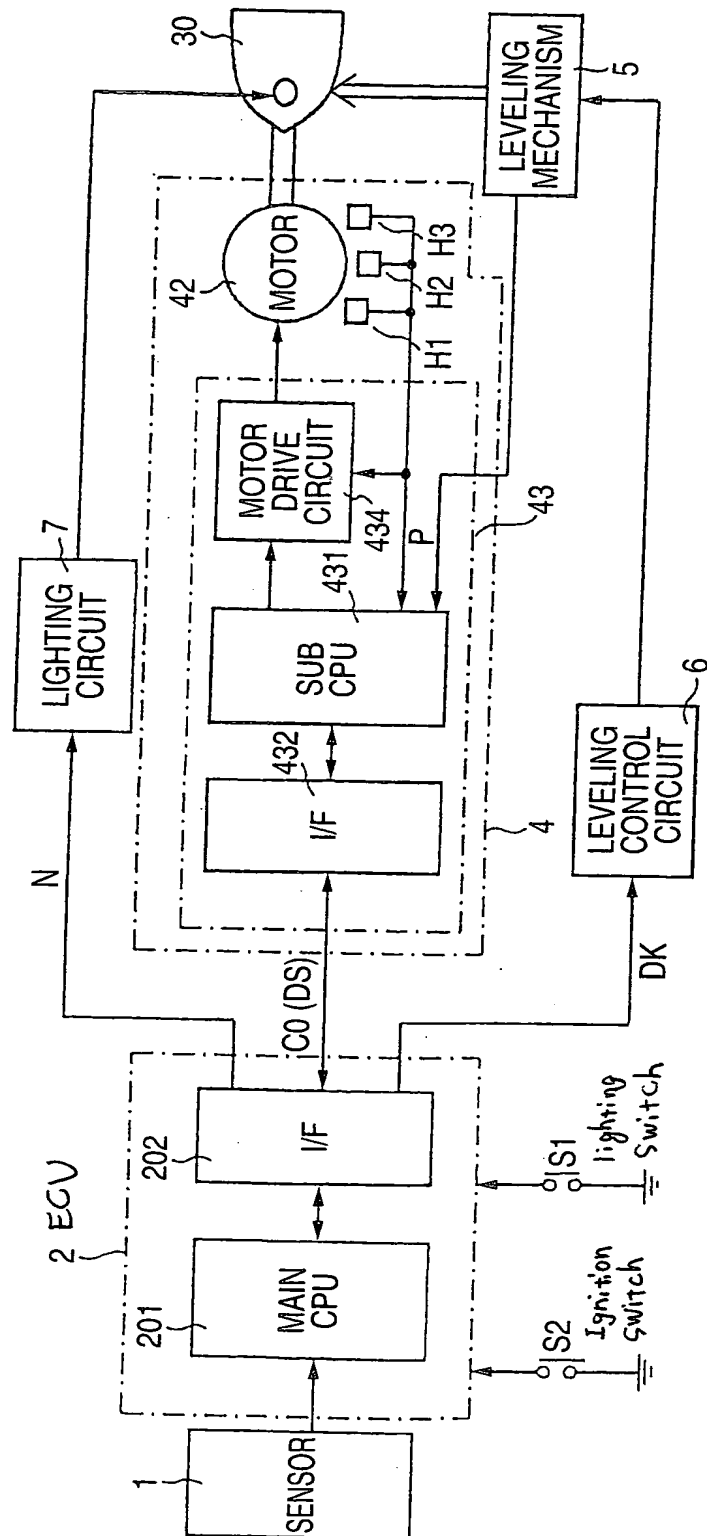


FIG. 10

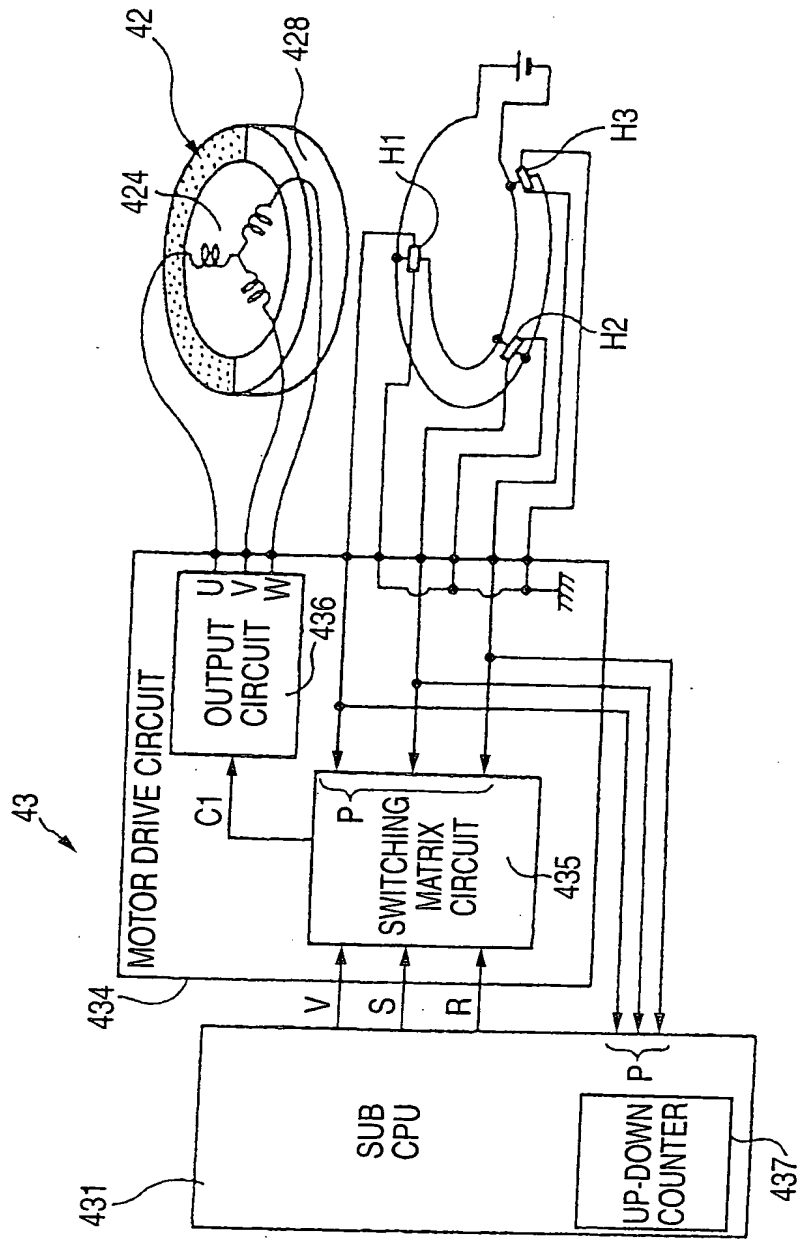


FIG. II

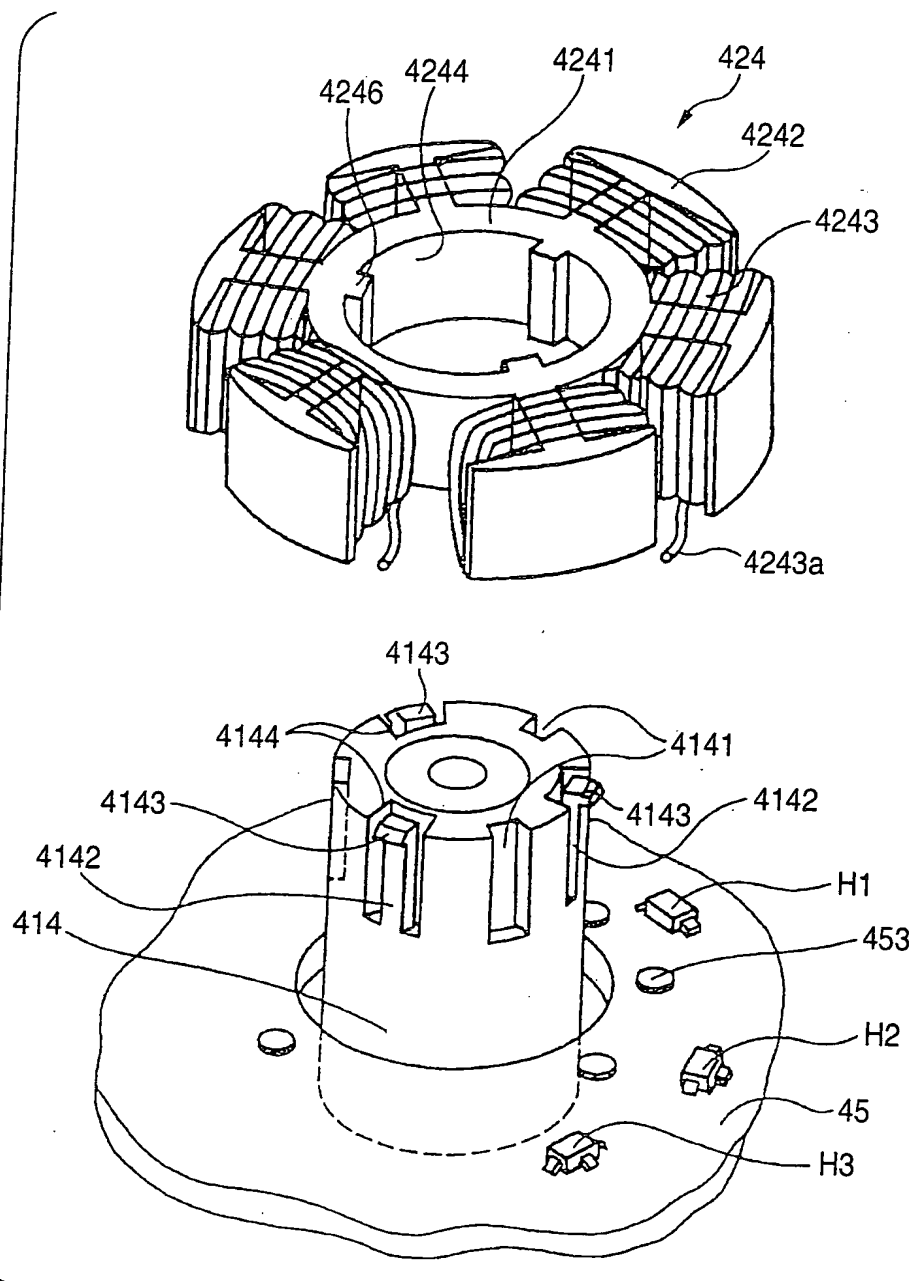


FIG. 12

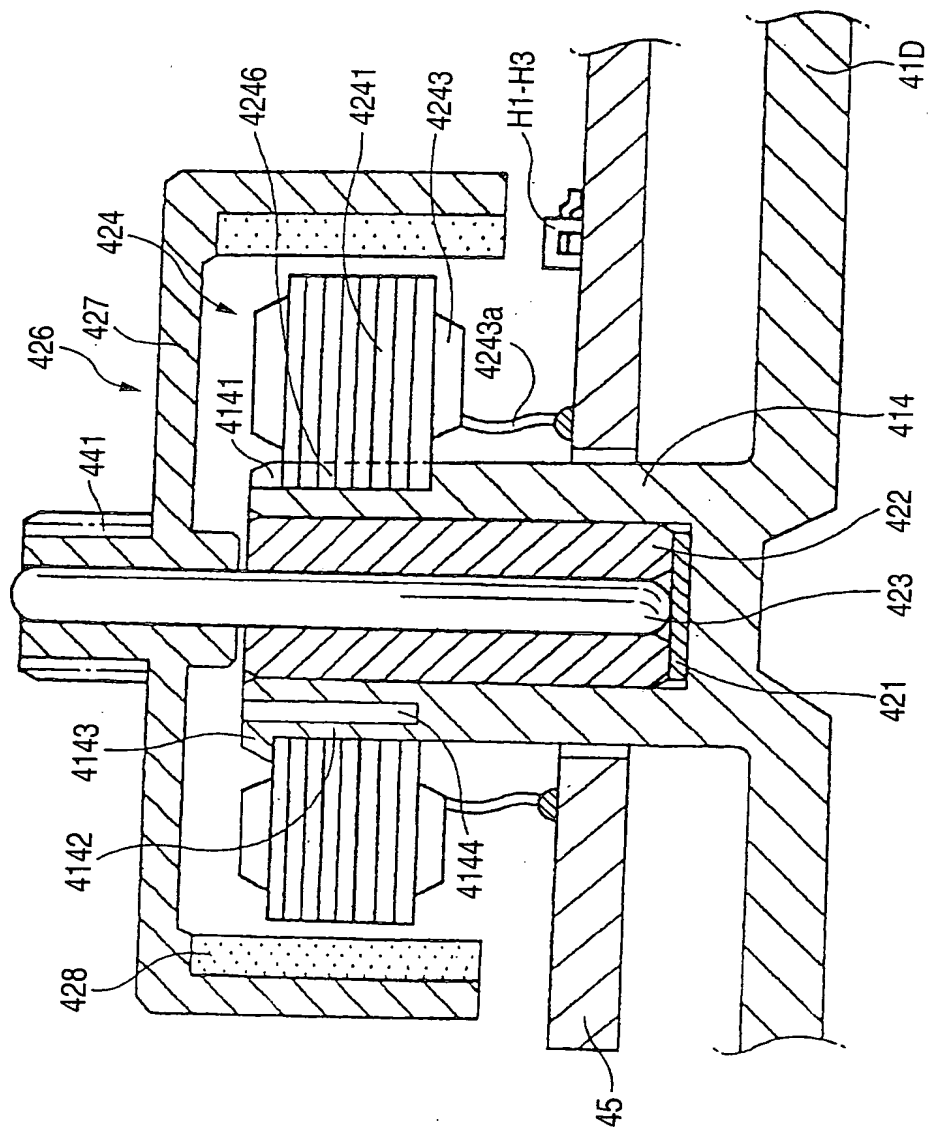


FIG. 13

